

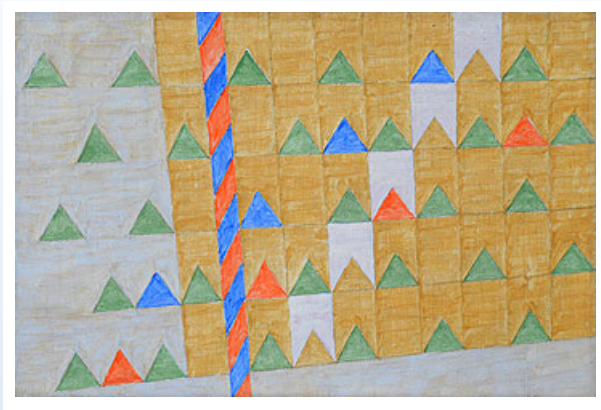
Ergodic measures with only (and many) zero exponents

Lorenzo J. Díaz

PUC-Rio

Luisenthal, October 1st

joint work with **J. Bochi (PUC-Rio)** and **Ch. Bonatti (Dijon)**.



Old title:

Robust vanishing of all Lyapunov exponents.

Hidden/implicit part of the title:

for **Iterated Function Systems** or **One Step skew products**.

Important: the multiple zero exponents hold for **open sets of systems** (robust)

are the measures robust ? (dependence of measures on maps)

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Construction of ergodic measures with some exponent zero
(non-hyperbolic measures).

Attention:

There are non-hyperbolic systems with *only* hyperbolic measures.

Two types of examples: critical and non-critical dynamics.

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Features:

- 1 All periodic orbits are hyperbolic,
- 2 Every ergodic measure is hyperbolic,
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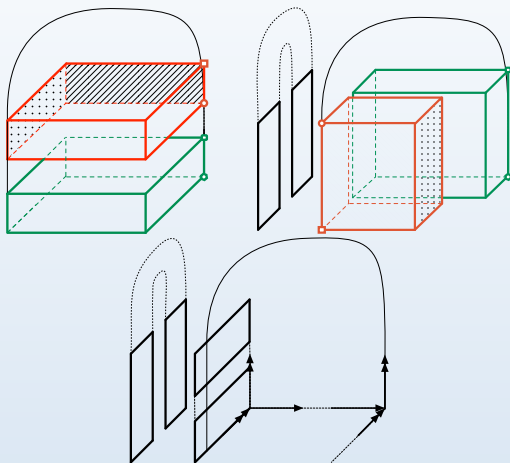
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([D,Horita,Rios,Sambarino], [Leplateur,Oliveira,Rios])

somewhat similar to Gelfert's talk.

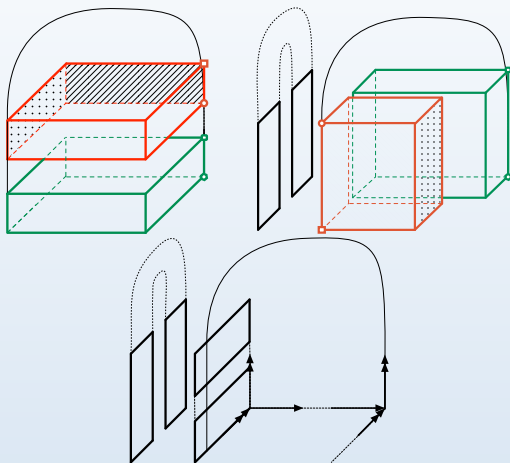


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Skew product and partial hyperbolicity

$$E^s \oplus E^c \oplus E^u$$

E^s stable, E^u unstable, E^c central.

- 1 Q is expanding in the E^c -direction,
- 2 all other periodic points are contracting along E^c ,
- 3 Ergodic measures (not Dirac at Q) are hyperbolic: two negative exponents (E^c, E^s) and a positive one (E^u).

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$f: M \rightarrow M$, μ **ergodic invariant measure**:

Oseledts splitting $T_x(M) = E_1(x) \oplus E_2(x) \oplus \cdots \oplus E_k(x)$
defined μ -a.e., dimension independent of x .

and **Lyapunov exponents** $\chi_1 < \chi_2 < \cdots < \chi_k$

$$\lim_{n \rightarrow \infty} \frac{\log \|Df^n(v)\|}{n} = \chi_j, \quad \forall v \in E_j(x) \setminus \{0\}, \quad \mu - \text{a.e. } x$$

$\dim E_j$ is the **multiplicity** of χ_j .

μ is **hyperbolic** if all exponents are non-zero.

number of zero exponents:

Λ transitive set with a Df -invariant splitting:

$$T_\Lambda M = E^s \oplus E^c \oplus E^u.$$

E^s uniformly contracting, E^u uniformly expanding,

E^c **central non-hyperbolic** part with **finest dominated splitting**

$$E^c = E_1 \oplus E_2 \oplus \cdots \oplus E_k$$

μ ergodic, χ_i exponent of μ relative to E_i ,

$$\chi_i = 0 \implies \chi_{j \neq i} \neq 0.$$

Conclusion: The number of zero exponents of an ergodic measure is $\leq \dim(E^c)$.

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$f_0, f_1: M \rightarrow M$, $\sigma: \{0, 1\}^{\mathbb{Z}} \rightarrow \{0, 1\}^{\mathbb{Z}}$ the shift map,

one-step skew products:

$$F: \{0, 1\}^{\mathbb{Z}} \times M \rightarrow \{0, 1\}^{\mathbb{Z}} \times M, \quad (\alpha, x) \mapsto (\sigma(\alpha), f_{\alpha_0}(x)).$$

Family of maps $(f_\alpha)_{\alpha \in \{0, 1\}^{\mathbb{Z}}}$, $f_\alpha: M \rightarrow M$, (nice dependence on α).

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Summary: Two scenarios (depending on the differentiability of the systems) where there are opens sets of one-step skew products with ergodic measures will all (fibered) exponents equal to zero.

C^2 dynamics

- 1 $[+]$ full support
- 2 $[+]$ constructive
(limit of periodic measures)
- 3 $[-]$ zero entropy

C^1 dynamics

- 1 $[-]$ support?
- 2 $[-]$ existence result
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$\sigma: \{0, 1, \dots, \ell - 1\}^{\mathbb{Z}} \rightarrow \{0, 1, \dots, \ell - 1\}^{\mathbb{Z}}$ is the **shift map**.

$g_0, \dots, g_{\ell-1}$ diffeomorphisms $g_i: M \rightarrow M$,

let $G = (g_0, \dots, g_{\ell-1})$ and the one-step skew product map

$$\varphi_G: \{0, 1, \dots, \ell - 1\}^{\mathbb{Z}} \times M \rightarrow \{0, 1, \dots, \ell - 1\}^{\mathbb{Z}} \times M,$$

$$\varphi_G(\alpha, x) = (\sigma(\alpha), g_{\alpha_0}(x))$$

Ergodic measures with all zero exponents and full support

Given any closed and compact M , $\dim M \geq 2$, there are ℓ and open set $\mathcal{U} \subset (\text{Diff}^2(M))^\ell$: for every $G = (g_0, \dots, g_{\ell-1}) \in \mathcal{U}$ the map

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has a compact invariant set Λ_G such that:

- 1 all exponents of any ergodic ν ($\text{supp}(\nu) \subset \Lambda_G$) are zero,
- 2 $h_{\text{top}}(G|_{\Lambda_G}) > 0$. So there is an ergodic μ with positive entropy and only zero exponents ($\text{supp}(\mu) \subset \Lambda_G$).

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- existence of an **attracting point with simple spectrum** - all exponents positive and different,
- **forward minimality**,
- **maneuverability**: “minimality in the space of directions”,
- implicit: there are no invariant directions, **no-domination**.
- **warning**: possibly the number ℓ is very big (!), this does not seem to be important in applications (we have in mind).
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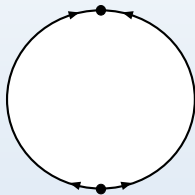
Intermingled horseshoes of different indices

Method for constructing ergodic measures with a zero exponent.
[Gorodetski-Ilyashenko-Kleptsyn-Nalsky]

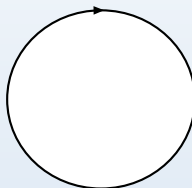
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$f_0: \mathbb{S}^1 \rightarrow \mathbb{S}^1$ pole north - pole south map,

$f_1: \mathbb{S}^1 \rightarrow \mathbb{S}^1$ irrational rotation (close to an irrational rotation)



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key feature **Minimality**: the system f_0, f_1 is forward minimal (the forward orbit of any point is dense in \mathbb{S}^1)

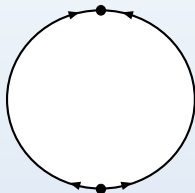
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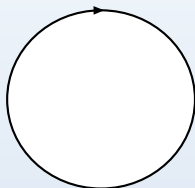
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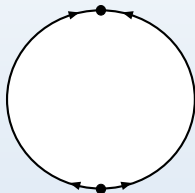
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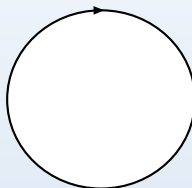
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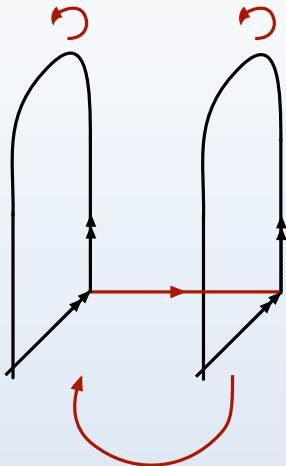


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Intermingled horseshoes

naive representation



Summary of previous results:

1-dimensional central direction.

- some one-step skew products over \mathbb{S}^1 [GIKN]
- general skew products over \mathbb{S}^1 [KN]
- open sets of diffeomorphisms in dimension ≥ 3 [KN]
- generic non-hyperbolic diffeomorphisms [DG], [BonattiDG]

have an **ergodic** measure with **full support** with a **zero exponent**.
This measure is a **weak-limit of periodic measures**.

- The ergodic measure is the **limit of a sequence of periodic measures**

$$\mu_n \rightarrow^* \mu.$$

- key one dimensional ingredient: **the exponent is an integral.**

$$\chi_c(\mu_n) \rightarrow \chi_c(\mu).$$

- This does not hold in higher dimensions.
Difficulty for obtaining measures with several zero exponents.
- key ingredient: **minimality** in the central directions (jump in finite time from an repeller to an attractor and vice-versa).
- Only C^1 -regularity is required.

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Several zero exponents: strategy

- 1 **Problem:** Consider skew products with higher dimensional central direction and construct systems with ergodic measures with all exponents equal to 0.
- 2 **Difficulty:** Exponents are not given by integral and thus they are not limits.
- 3 **Trick:** Rewrite exponents as integrals (recovering continuity).
- 4 **Ingredient:** Flag dynamics (a dynamics induced in the space of flags of the tangent bundle).
- 5 **Price:** Increase differentiability. C^1 -dynamics in the space of flags $\implies C^2$ -dynamics in the ambient.

Programm: Repeat the one-dimensional procedure: one-step skew products \rightarrow skew products \rightarrow open sets \rightarrow generic dynamics.

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Programm: Repeat the one-dimensional procedure: one-step skew products \rightarrow skew products \rightarrow open sets \rightarrow generic dynamics.

Several zero exponents: strategy

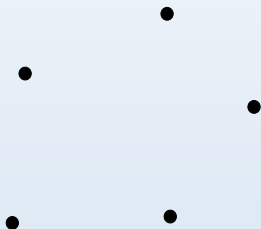
- 1 **Problem:** Consider skew products with higher dimensional central direction and construct systems with ergodic measures with all exponents equal to 0.
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improved method of Gorodetski-Ilyashenko-Kleptsyn-Nalsky for constructing ergodic measures as limits of periodic measures (version in [BDG]).

initial periodic orbit (and periodic measure)



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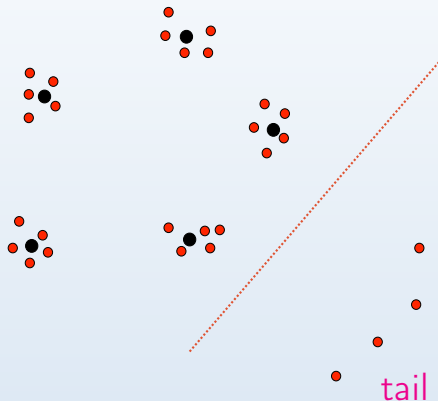
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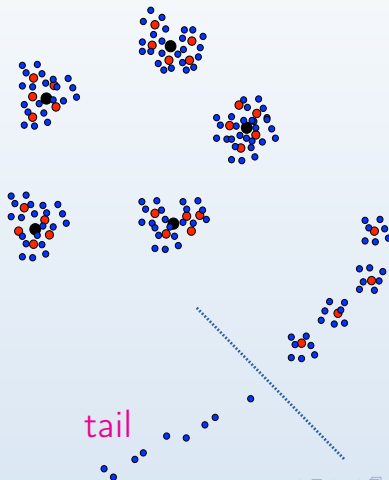
ergodic limit of periodic measures (II)

a second orbit mimics the first one most of the time (fixed proportion) and has a **tail**.



ergodic limit of periodic measures (III)

a third orbit mimics the second one most of the time (fixed proportion) and has a **tail**.



ergodic limit of periodic measures (IV)

two **effects** of the tail:

- spread the support of the limit measure: the support of the measure is

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- approach the exponent to zero:

- ① n -th orbit P_n with exponent χ_n , a pivot auxiliary orbit with exponent $\simeq 0$
- ② $(n+1)$ th orbit P_{n+1} mimics P_n 90% of time and Q 10% of time,
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Flags and flag dynamics

Everything You Always Wanted to Know About Flags But Were Afraid to Ask.

Flags in 5 minutes!



Flags and flag dynamics

\mathbb{V} vectorial space of dimension d .

$$\mathbb{F}_1 \subset \mathbb{F}_2 \subset \cdots \subset \mathbb{F}_n = \mathbb{V}, \dim \mathbb{F}_i = i.$$

Flag $\mathbb{F} = (\mathbb{F}_1, \mathbb{F}_2, \dots, \mathbb{F}_d).$

(Forgetting orientation) flag \simeq orthonormal basis:

$$F = \{f_1, \dots, f_d\}, \{f_1, \dots, f_j\} \text{ orthonormal basis of } \mathbb{F}_j.$$

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$L: \mathbb{V} \rightarrow \mathbb{W}$ linear isomorphism.

induced map in the flag space:

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Using orthonormal basis the flag action of L has a triangular form.
This will simplify calculations.

$TM, T_x M$

flag manifold $\mathcal{F}M$, the fiber of x consists of the flags of $T_x M$.

This resembles the **Grassmannian space**.

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Reformulation of the main result for flags (stronger version):

Ergodic measures with all zero exponents

Given any closed and compact M , $\dim M \geq 2$, there are ℓ and open set $\mathcal{U} \subset (\text{Diff}^2(M))^\ell$: for every $G = (g_0, \dots, g_{\ell-1}) \in \mathcal{U}$ the map

$$\varphi_{\mathcal{F}G}: \{0, \dots, \ell - 1\}^{\mathbb{Z}} \times M \rightarrow \{0, \dots, \ell - 1\}^{\mathbb{Z}} \times M,$$

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has an ergodic measure with full support and whose exponents are all zero. This measure is a limit of periodic measures.

Notations, ingredients:

X compact metric space, $T: X \rightarrow X$, homeomorphism.

\mathbb{V} vector bundle over X .

a projection $\pi: \mathbb{V} \rightarrow X$.

$S: \mathbb{V} \rightarrow \mathbb{V}$ vector bundle linear isomorphism, $\pi \circ S = T \circ \pi$.

$$\mathbb{V}_x = \pi^{-1}(x), \quad S_x^{(n)}: \mathbb{V}_x \rightarrow \mathbb{V}_{T^n(x)}.$$

S induces the map $\mathcal{FS} \dots$ acting on the flag bundle \mathcal{FV} .

ν ergodic measure (in the flag bundle \mathcal{FV}) of \mathcal{FS} .

Furstenberg vector:

$$\overrightarrow{\Lambda(\nu)} = (\Lambda_1(\nu), \dots, \Lambda_d(\nu))$$

$$\Lambda_j(\nu) = \int_{\mathcal{FV}} \log |\det S_x|_{\mathbb{F}_j} d(\nu, \mathbb{F}), \quad \mathbb{F} = (\mathbb{F}_1, \dots, \mathbb{F}_d).$$

key move! the numbers $\Lambda_j(\nu)$ (thus $\overrightarrow{\Lambda(\nu)}$) are defined as integrals and thus depend continuously on the weak* topology.

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Exponents and determinants

Let χ_1, \dots, χ_d the exponents of S . Then there is a permutation i_1, \dots, i_d of $(1, \dots, d)$ such that

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Exponents of the flag maps

The exponents of \mathcal{FS} are of the form $\chi_{i_j} - \chi_{i_k}$.

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End of the proof....

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$$0 > \chi_1(z) > \chi_2(z) > \cdots > \chi_d(z).$$

$E_1(z), E_2(z), \dots, E_d(z)$ eigendirections.

stable flag of z (an attracting flag):

$$S(z) = (E_1(z), E_1(z) \oplus E_2(z), \dots, E_1(z) \oplus \cdots \oplus E_d(z)).$$

attracting points z_n with attracting flags $S(z_n)$ such that

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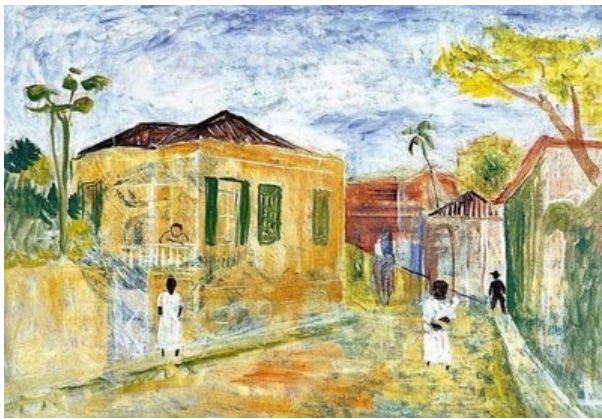
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Thanks!



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cone $C = \{\vec{\lambda} = (\lambda_1, \dots, \lambda_d) : 0 > \lambda_1 > \dots > \lambda_d\}$.

projective map $\Gamma : C \rightarrow \mathbb{R}^+$, $\Gamma(t\vec{\lambda}) = \Gamma(\vec{\lambda})$

generation of orbits

Given $(z, S(z))$ stable flag, $\vec{\chi}(z)$ (Lyapunov vector)

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(there are some quantifiers.... ϵ, δ, κ)

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- ① allows to repeat the procedure,
- ② exponents go to 0^d ,
- ③ criterium of the ergodic measures,
- ④ as $\delta \rightarrow 0$ the supp periodic measures increase.