Generic Symplectic Diffeomorphisms and Partial Hyperbolicity

Workshop on Symplectic Dynamics Institute for Advanced Study (Princeton)

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Plan of the talk

- Recall basic definitions.
- State a theorem on partial hyperbolicity of generic symplectic diffeomorphisms.
- Discuss consequences and further developments of that theorem (including the ergodicity result).
- Compare with a cousin theorem for volume-preserving diffeomorphisms.
- Sketch the main ideas of the proof, and so expain:
 - why symplectic is more difficult than volume-preserving;
 - the probabilistic method for constructing the perturbations.

Lyapunov exponents, Oseledets splitting

 $f: M \to M$ diffeomorphism of a compact manifold of dimension d. By the **Oseledets theorem**, there exists a full probability set $R \subset M$ such that for every (*regular point*) $x \in R$ there is a (*Oseledets*) splitting

$$T_x M = E^1(x) \oplus \cdots \oplus E^{k(x)}(x)$$
, (each $\neq \{0\}$)

and numbers (Lyapunov exponents) $\Re_1(x) > \cdots > \Re_{k(x)}(x)$ such that

$$\frac{1}{n}\log\|Df^n(x)\cdot v\|\xrightarrow[n\to\pm\infty]{}\widehat{\mathcal{R}}_i(x)\quad\forall\,v\in E^i(x)\smallsetminus\{0\}.$$

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The *zipped Oseledets splitting* is obtained by summing together all spaces with exponents of the same sign:

$$T_x M = E^+(x) \oplus E^0(x) \oplus E^-(x).$$

 $(E^*(x) = \{0\} \text{ now allowed, of course.})$

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Lyapunov exponents, Oseledets splitting (continued)

The multiplicity of each Lyapunov exponent $\Re_j(x)$ is dim $E^j(x)$ (by definition).

Indicate the Lyapunov exponents repeated according to multiplicity by:

$$\lambda_1(x) \ge \lambda_2(x) \ge \cdots \ge \lambda_d(x), \qquad (d = \dim M).$$

If f preserves a symplectic form ω on M then (d is even and) the exponents are symmetric:

$$\lambda_1 = -\lambda_d, \quad \lambda_2 = -\lambda_{d-1}, \quad \dots \quad , \quad \lambda_{\frac{d}{2}} = -\lambda_{\frac{d}{2}+1}.$$

In particular, if $T_x M = E^+(x) \oplus E^0(x) \oplus E^-(x)$ is the zipped Oseledets splitting then

$$\dim E^+(x) = \dim E^-(x)$$
, $\dim E^0(x) = \text{even}$.

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$$\forall n \ge 0, \begin{cases} \|Df^{n}(x) \cdot v^{s}\| \le C\tau^{-n}\|v^{s}\| & \forall v^{s} \in E^{s}(x) \setminus \{0\} \\ \|Df^{-n}(x) \cdot v^{u}\| \le C\tau^{-n}\|v^{u}\| & \forall v^{u} \in E^{u}(x) \setminus \{0\} \end{cases}$$

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- **2** A splitting $T_{\Lambda}M = E^u \oplus E^c \oplus E^s$ is called *partially hyperbolic* if:
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Remark: These bundles are automatically uniformly continuous, and thus extend (with the same hyperbolicity properties) to the closure \mathbb{X} .

Domination: the weakest uniform form of hyperbolicity

If E, F are Df-invariant subbundles of $T_{\Lambda}M$ then we say that E dominates F (in symbols, E > F), if there are constants c > 0, $\tau > 1$ such that for all unit vectors $\vec{e} \in E(x)$, $\vec{f} \in F(x)$ and all $n \ge 0$

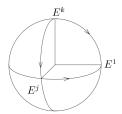
$$\frac{\|Df^n(x)\cdot\vec{e}\|}{\|Df^n(x)\cdot\vec{f}\|} > c\tau^n.$$

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Dominated splitting: $T_{\Lambda}M = E^1 \oplus \cdots \oplus E^k$ with $E_1 > E_2 > \cdots > E_k$. "Morse–Smale-like" dynamics on projective space:



Domination is a.k.a. (in ODE theory) as *exponential separation*. It dates back to Perron (rediscovered by Mañé.)

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Moreover, the 2nd alternative occurs for a positive μ -measure set of points $x \in M$ if and only if $f \in \mathcal{R}$ is Anosov.

Rem.: A weaker version (with no PH) was proved earlier in [B., Viana '05].

Discussion: $\dim M = 2$

If $\dim M = 2$ then the 3rd alternative in the theorem (partial hyperbolicity with 3 bundles) is impossible, so we get:

Corollary (B. '02)

 C^1 -generic area-preserving diffeomorphisms are either Anosov or have zero Lyapunov exponents almost everywhere.

Rem.: The proof of this result appeared much before, and relied heavily on Mañé's ideas.

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One can break M (minus a zero set) invariantly:

$$M = Z \sqcup \coprod \Lambda_n \mod 0$$
 where
$$\left\{ \begin{array}{l} Z = \{ \text{all } \lambda_i = 0 \}, \\ \Lambda_n = \text{partially hyperbolic sets} \end{array} \right.$$

- Each Λ_n (or its closure N_n) has of course its hyperbolicity constants c_n , τ_n .
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- However, these constants become weaker and weaker as *n* grows.

Please note that this is much stronger than what's is given by Oseledets theorem, which gives no uniformity along the orbits.

Also note that if $f \in \mathcal{R}$ is *ergodic* then the situation is much simpler. . .

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Proof of the theorem: Just combine the previous theorem with this:

Theorem (Corollary of Dolgopyat–Wilkinson)

Generic $f \in PH^1_{\omega}(M)$ are (accessible and) weakly ergodic (i.e., almost every point has a dense orbit).

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Nice thing: The zero exponents in the center give a *nonuniform version of Burns–Wilkinson's center bunching*.

Ergodicity

Indeed many of Burns–Wilkinson's arguments work with *nonuniform center bunching*.

Putting these together with other [non obvious!] arguments, we get:

Theorem (Avila, B., Wilkinson '09)

The generic $f \in PH^1_{\omega}(M)$ is ergodic.

(Curiosity: This paper was published before its ancestors [BW'10] and [B'10].)

This gives a C^1 -generic, symplectic version of the Pugh–Shub ergodicity conjecture.

Proofs?

Now let's give an idea of the proof of the theorem stated by Mañé:

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For every f in a residual (dense G_{δ}) subset \mathscr{R} of $\mathrm{Diff}^1_{\omega}(M)$, the following properties hold: For μ -a.e. $x \in M$, the zipped Oseledets splitting $T_{\Lambda}M = E^+ \oplus E^0 \oplus E^-$ on $\Lambda = \mathrm{orb}(x) = \{f^n(x); n \in \mathbb{Z}\}$ is:

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For the "moreover" part, we show that for C^2 (and hence C^1 -generic) diffeos, hyperbolic sets have either zero or full measure. [B., Viana '04].

Back to basics: domination, and the symplectic case

In fact, to prove the result above, one "only" needs to show the following:

Theorem (Main Theorem)

If f is generic in $\mathrm{Diff}^1_\omega(M)$ then for almost every $x \in M$, the Oseledets splitting along the orbit of x is either trivial or dominated.

A Df-invariant splitting $T_{\Lambda}M = E^1 \oplus \cdots \oplus E^k$ is called

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Then, to conclude the proof of Mañé's statement, one has to use that for symplectic maps, "domination implies partially hyperbolicity". [B., Viana '04].

Rem.: Actually we obtain more information than in Mañé's statement, since also get domination between different exponents of the same sign.

Comparison with the volume-preserving case

The "Main Theorem" just stated is also true replacing "symplectic" by "volume-preserving":

Theorem (B. Viana '05)

If f is generic in $\operatorname{Diff}^1_{VOI}(M)$ then for almost every $x \in M$, the Oseledets splitting along the orbit of x is either trivial or dominated.

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Rem.: There are some recent "global" improvements of this result: Avila–B. (ArXiv 2010), Jana Rodriguez–Hertz (in preparation), but that's another story...

Another reduction

Integrated summed Lyapunov exponent:

$$L_{p}(f) = \int_{M} (\lambda_{1} + \dots + \lambda_{p}) d\mu$$
$$= \int \left(\lim_{n \to \infty} \log \| \wedge^{p} (Df^{n}) \| \right) d\mu.$$

Easy fact: L_p : $\mathsf{Diff}^1_\omega(M) \to \mathbb{R}$ is upper-semicontinuous, and thus continuous on a residual subset.

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Strategy of the proof: Suppose that one can detect non-domination of the Oseledets splitting on a positive measure set. Then produce a perturbation of f for which some L_p drops.

Fix f, $p \in \{1,..., N = d/2\}$. Assume that the following set has positive measure:

 $\Sigma_p = \{x \in M; x \text{ regular non periodic with } \lambda_p(x) > \lambda_{p+1}(x)\}$

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$$T_{\Sigma_p}M = E^u \oplus E^c \oplus E^s$$
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$$\begin{cases} \dim E^u = \dim E^s = p \\ \dim E^c = 2(N-p) \end{cases}$$

Misleading notation: the splitting is not PH!

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Denote $E^{uc} = E^u \oplus E^c$ etc. Then

$$\omega \left(E^{u},E^{uc}\right) \equiv \omega \left(E^{c},E^{us}\right) \equiv \omega \left(E^{s},E^{cs}\right) \equiv 0.$$

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Main steps (sketchy)

• If a point in Σ_p "sees" non-domination $E^u \not\succ E^{cs}$ (for example, if $\sphericalangle(E^u, E^{cs})$ is small) then we can find a perturbation g of f that sends a vector from E^u_f to E^{cs}_f .

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- Do that in the *middle* of a long segment of orbit $\{x,...,f^nx\}$. Then one gets

$$\frac{1}{n}\log\|\wedge^p Dg^n(x)\| < \lambda_1(f,x) + \dots + \lambda_p(f,x) - \text{Something}.$$

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- If a point in Σ_p "sees" non-domination $E^u \not\succ E^{cs}$ (for example, if $\sphericalangle(E^u, E^{cs})$ is small) then we can find a perturbation g of f that sends a vector from E^u_f to E^{cs}_f .
- Do that in the *middle* of a long segment of orbit $\{x,...,f^nx\}$. Then one gets

$$\frac{1}{n}\log\|\wedge^p Dg^n(x)\| < \lambda_1(f,x) + \dots + \lambda_p(f,x) - \text{Something}.$$

- ► Something = $\frac{1}{2}(\lambda_p(f,x) + \lambda_{p+1}(f,x))$ (which is POSITIVE).
- ▶ In fact we should obtain the inequality not only for x [a zero measure set is useless], but for most z around x in the support of the perturbation.

Main steps (continued)

Example: $\dim M = 2$

$$Df^{n}(x) = \begin{pmatrix} 2 & 0 \\ 0 & 1/2 \end{pmatrix}^{k} \operatorname{Id}^{m} \begin{pmatrix} 2 & 0 \\ 0 & 1/2 \end{pmatrix}^{k}, \qquad k \simeq n/2 \gg m \gg 1.$$

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[draw a figure with the solution]

Back to the steps of the general proof:

- Around a segment of orbit $\{x, ..., f^n x\}$ that sees nondomination we find a thin and long tower $U \sqcup f(U) \sqcup \cdots \sqcup f^n(U)$, and find a perturbation supported in the tower so that the "finite-time" summed exponent drops (as explained above).
- Cover the a ("large") positive measure set of the manifold with these towers.
- This causes a significant drop of $L_p = \int (\lambda_1 + \cdots + \lambda_p)$, as we wanted.

The 4 types of non-dominance

Assume $x \in \Sigma_p$ and the segment of orbit $\{x, ..., f^m x\}$ is very long $(m \gg 1)$ and "sees" non-domination $E^u \not\succ E^{cs}$; more precisely:

$$\frac{\|Df^{m}(x)|E^{cs}(x)\|}{\mathfrak{m}(Df^{m}(x)|E^{u}(x))} \ge \frac{1}{2}. \qquad (\mathfrak{m}(L) = \|L^{-1}\|^{-1}).$$

Lemma (of Symplectic Linear Algebra): one of the following 4 cases occurs:

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Case I: small angle. There is a point $y \in \{x,...,f^mx\}$ such that $\sphericalangle(E^{cs}(y),E^u(y))\ll 1$.

How to perturb it: Compose with a single small rotation.

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Case I: small angle. There is a point $y \in \{x,...,f^mx\}$ such that $\triangleleft (E^{cs}(y),E^u(y)) \ll 1$.

How to perturb it: Compose with a single small rotation.

Case II: inverted behaviors. There are unit vectors $v^{cs} \in E^{cs}(x)$, $v^u \in E^u(x)$ such that $\|Df^m(x) \cdot v^{cs}\| \gg \|Df^m(x) \cdot v^u\|$. (Replace if necessary the whole segment of orbit by a subsegment.)

How to perturb it: Use two small rotations, one at the beginning and the other at the end.

Case III: Identity on a symplectic $(\omega \neq 0)$ plane.

There is a long subsegment of orbit such the following holds: There is a (2-dim) plane spanned by a vector in E^u and a vector in E^s such that the restriction of Df to this plane "looks like the identity" (or more precisely, becomes an isometry after a bounded change of coordinates).

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How to perturb it: This case is essentially 2-dimensional. Use several "nested" rotations, as explained in a previous example. . .

Case IV: Expansion on a null $(\omega \equiv 0)$ plane.

There is a (2-dim) plane P spanned by a vector in E^u and a vector in E^c which is **uniformly expanded** and **conformal** (along the segment of orbit). That is, after a bounded change of coordinates we have

$$Df(f^ix)|P = \begin{pmatrix} \tau_i & 0 \\ 0 & \tau_i \end{pmatrix}, \qquad \tau_i > c > 1.$$

The plane is necessarily null $(\omega \equiv 0)$.

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However, this perturbation is not symplectic!

(In the **volume-preserving** case this idea would work; there are only 3 cases to be considered there.)

4-dimensional problem

There are standard symplectic coordinates $p_1, \ldots, p_N, q_1, \ldots, q_N$ (so $\omega = \sum_i dp_i \wedge dq_i$) such that

$$P = \left\langle \frac{\partial}{\partial p_{1}}, \frac{\partial}{\partial p_{2}} \right\rangle,$$

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$$\left\langle \tau \right\rangle$$

$$Df|P \oplus Q = \begin{pmatrix} \tau_i & & \\ & \tau_i & \\ & & \tau_i^{-1} & \\ & & & \tau_i^{-1} \end{pmatrix} \quad \text{(order: } p_1, p_2, q_2, q_1.\text{)}$$

If we rotate P we also need to rotate Q.

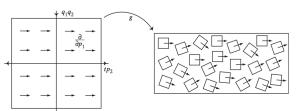
Nested rotations don't work! The problem is that hyperbolicity of Df quickly distorts the domain where the perturbation should be supported.

• Start with a box D as a perturbation domain. (We can pretend $M = \mathbb{R}^4$.)

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- Let Θ_0 be the angle (in the p_1p_2 projection) that the field of directions $v_0 = \frac{\partial}{\partial p_1}$ is rotated as we apply h. View Θ_0 as a **random variable**. (Normalize measure $\mu(D) = 1$).

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- Look the image g(D) and the image v_1 of the field $v_0 = \frac{\partial}{\partial p_1}$ by Dg. Using Vitali Lemma, cover most of g(D) by many disjoint tiny boxes D_i that look like (basically after a change of scale) the original box:



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- Then THE RANDOM VARIABLES Θ_0 AND Θ_1 ARE (approximately) INDEPENDENT AND IDENTICALLY DISTRIBUTED!
- Continuing this process we obtain a RANDOM WALK $S_n = \Theta_0 + \Theta_1 + \cdots + \Theta_n$.
- Since every (non-stopped) random walk is transient, most orbits eventually reach $\pm \pi/2$.
- Thus we succeeded in sending the direction $\frac{\partial}{\partial p_1} \in E^u$ to the direction $\frac{\partial}{\partial q_1} \in E^c$ (for most points).



The end

THANK YOU!